

```
1 // MotorsLib.h
2
3 #ifndef MotorsLib_h
4 #define MotorsLib_h
5
6 #include "Arduino.h"
7
8 class MotorsLib{
9
10    public:
11        int enable12;
12        int enable34;
13        int input1;
14        int input2;
15        int input3;
16        int input4;
17        MotorsLib ();
18        MotorsLib (int m_enable12, int m_enable34);
19        MotorsLib (int m_enable12, int m_enable34, int m_input1, int m_input2, int
m_input3, int m_input4);
20        void PararMotores();
21        void IrAdelante();
22        void IrAtras();
23        void GirarDerecha();
24        void GirarIzquierda();
25
26    private:
27
28 };
29
30#endif
```